



# ***Safety Boxes Sizing for Controlled Re-entry Application to ATV***

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- ✓ **Context**
- ✓ *Simulations*
- ✓ *Statistics*
- ✓ *Conclusions*

## ✓ Automated Transfer Vehicle

- ❑ Mission: logistic servicing of the ISS
- ❑ 20 tons (injection), 12 tons (nominal end of mission)
- ❑ Re-entry analysis: many surviving fragments

⇒ **Controlled re-entry**

## ✓ At system level: Global risk analysis

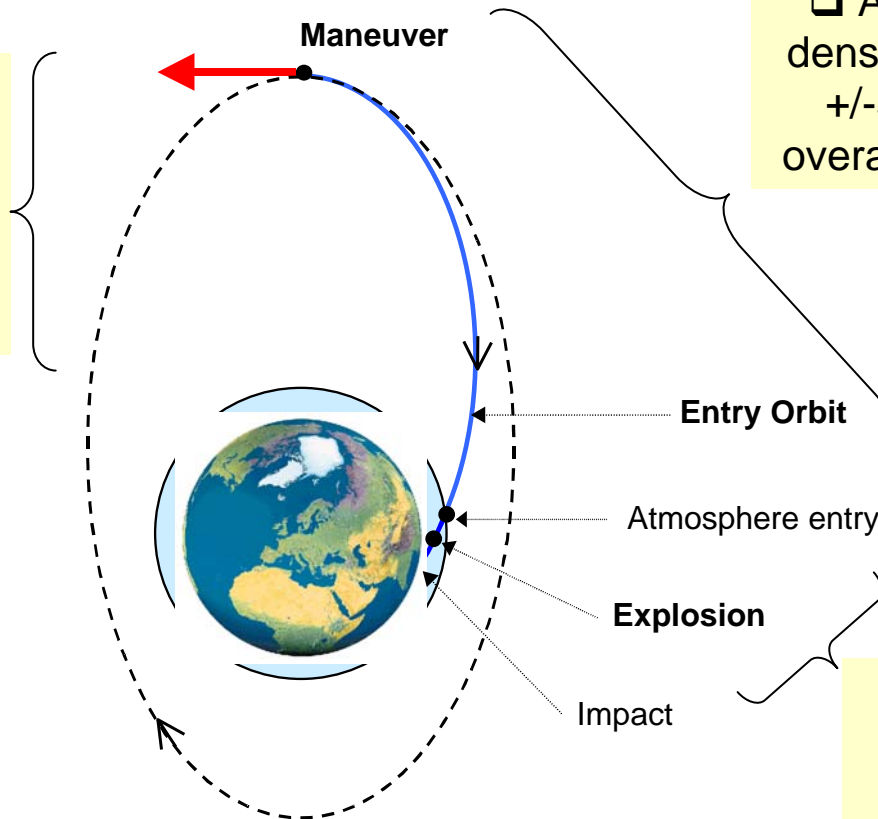
## ✓ At ATV-CC level: **Safety boxes computation for trajectory design and operations**

- ❑ Containment contour on the ground such that the probability to have a fragment falling outside corresponds to a given level (P)
  - Declared Re-entry Area :  $P = 10^{-2}$  ⇒ NOTAM
  - Security Re-entry Area :  $P = 10^{-5}$  ⇒ Trajectory design

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## Main Dispersions sources that influence ATV controlled re-entry

- Delta V: Gaussian
- Thrust level: Uniform
- Thrust orientation: Gaussian
- Mass: Gaussian,  $3\sigma = 320$  kg



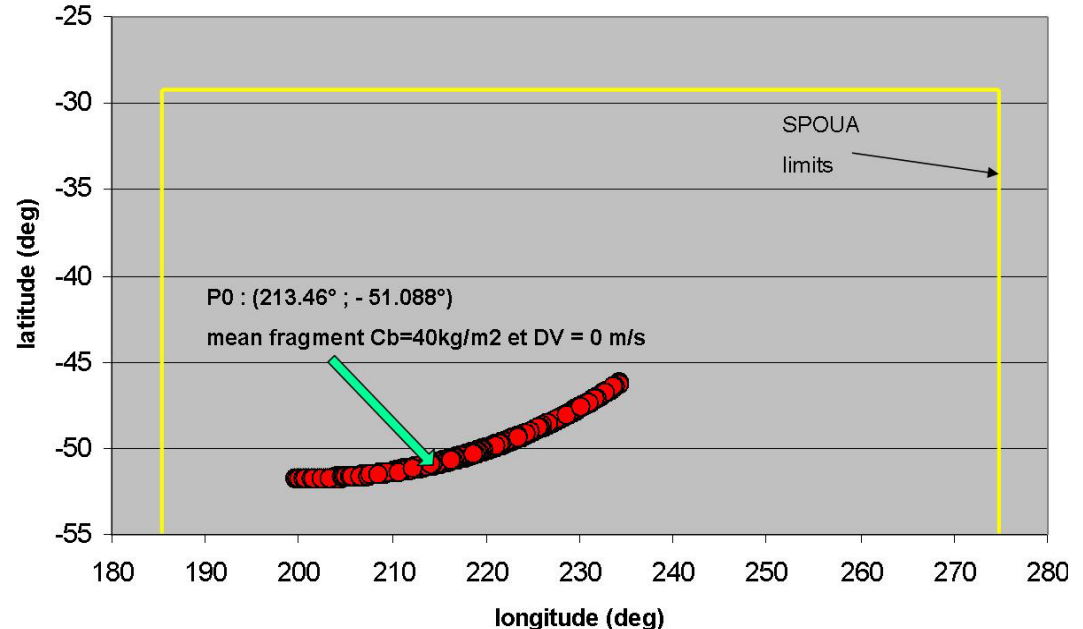
- Atmospheric density: Uniform +/-50% for the overall trajectory

- Break-up / Explosion modeling

- ✓ Severe heating environment
  - ❑ Break-up or Explosion produces fragments
  - ❑ Fragment main characteristics: initial state vector,  $C_b$ , material
  - ❑ Survivability
  
- ✓ For safety boxes, a single fragmentation step occurs
  - ❑ A sample of fragments covering a very large range of  $C_b$
  - ❑ Module of ejection velocities depends on the propellant filling
  
- ✓ Dispersions
  - ❑ Altitude of explosion: Gaussian 75 km,  $\sigma = 2$  km
  - ❑ Fragments ballistic coefficient: Uniform
  - ❑ Fragments ejection velocity direction: Uniform

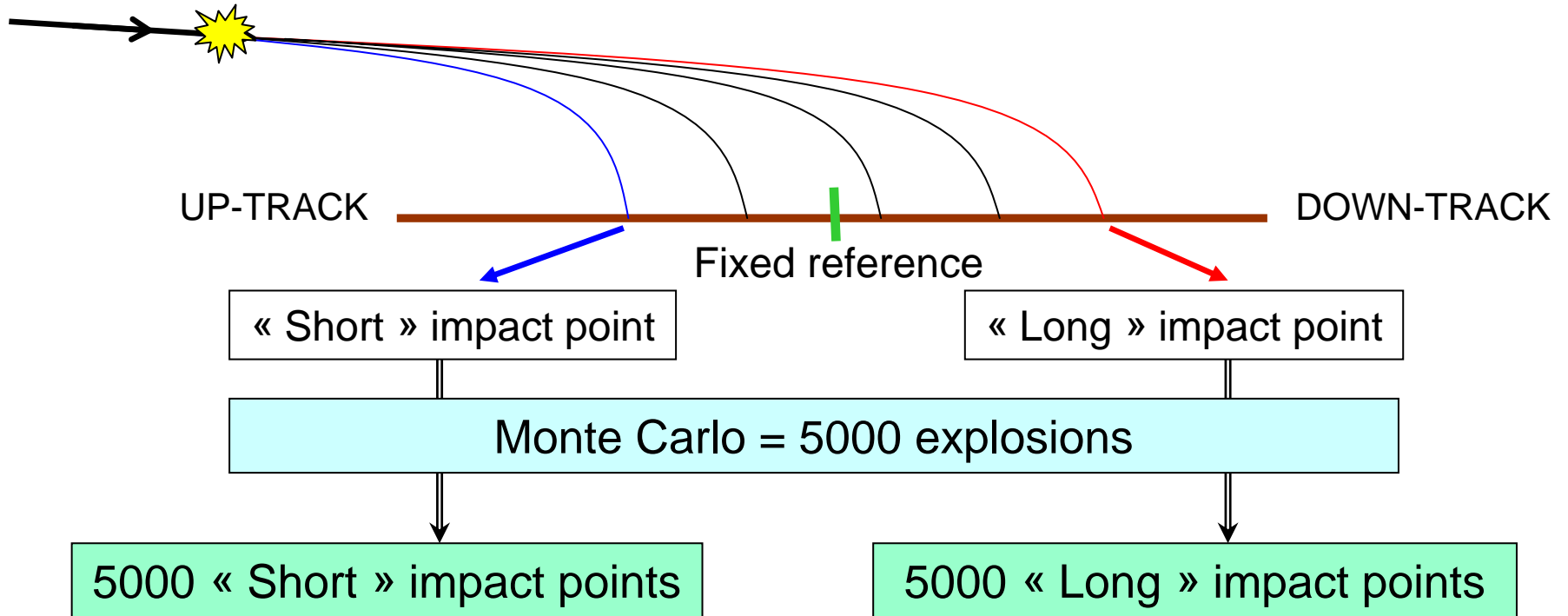
Dispersions sources are simulated together to assess the overall effect  $\Rightarrow$  **Monte-Carlo method** (5000 simulations)

✓ Footprint analysis



✓ The problem can be restrain in one dimension

## ✓ Typical explosion

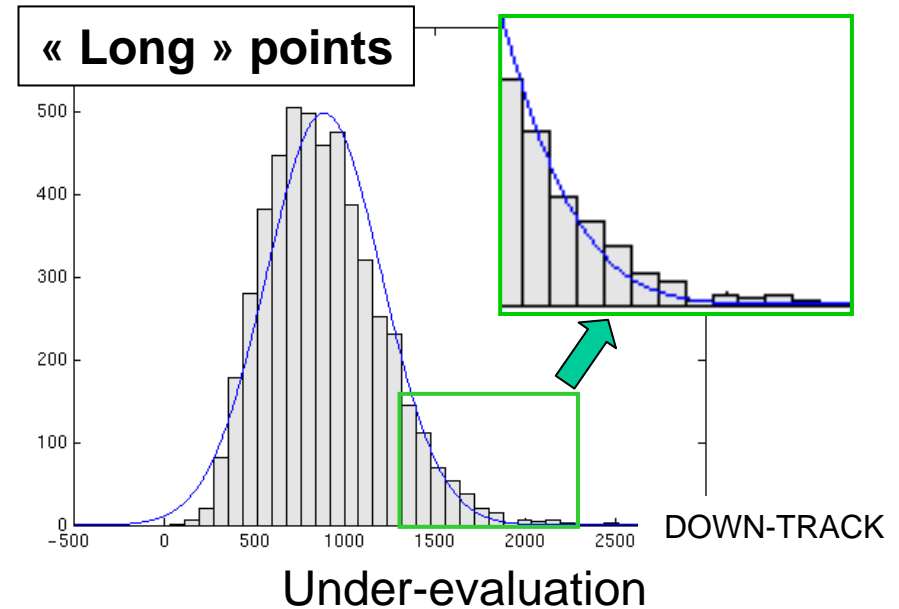
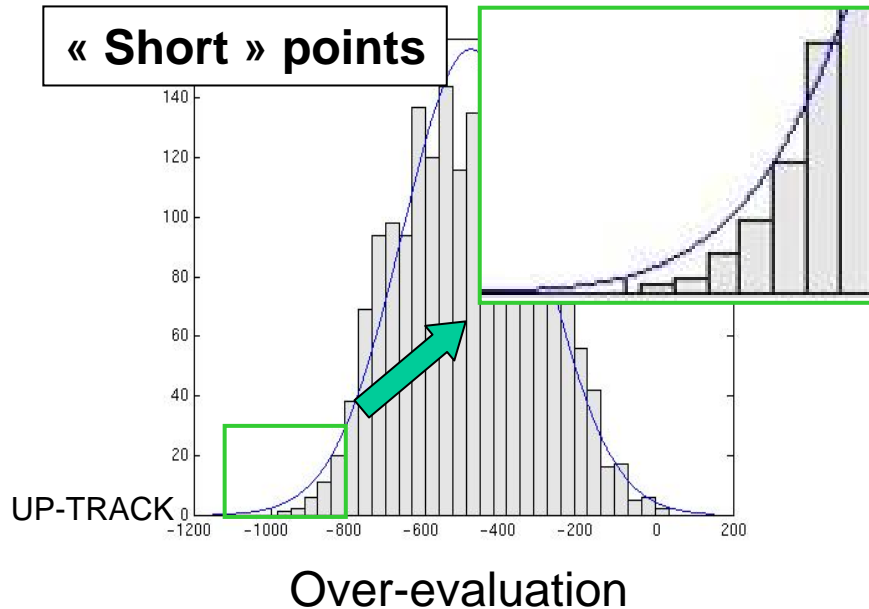


## ✓ Probabilities must be derived

- from “Short” point distribution for up-track boundary
- from “Long” point distribution for down-track boundary

- ✓ *Context*
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## Gaussian approach



- ❑ Does not match the histogram for low probability density regions
- ❑ Numerical comparison between Gaussian law and the empirical cumulative density of probability shows important deviations
- ✓ Gaussian method is not appropriate for computing safety boxes

## Extreme values prediction

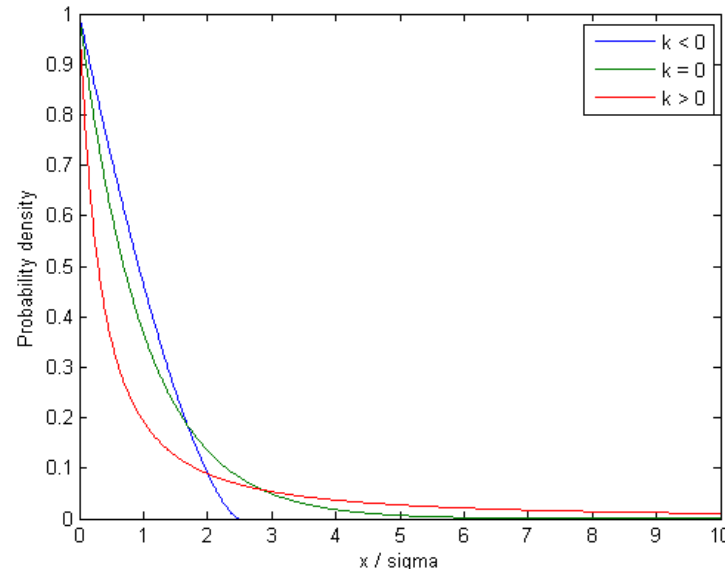
- ✓ There are specific techniques to deal with tails of distribution
  - ❑ Extreme floods prediction, ...

## ✓ Generalized Pareto Distribution

- ❑ A family of distribution
- ❑ Models a wide variety of tail of distribution

$$f(x) = \begin{cases} \frac{1}{\sigma} \cdot \left( 1 + k \cdot \frac{(x - \mu)}{\sigma} \right)^{-1 - 1/k} & k \neq 0 \\ \frac{1}{\sigma} \cdot \exp\left(-\frac{(x - \mu)}{\sigma}\right) & k = 0 \end{cases}$$

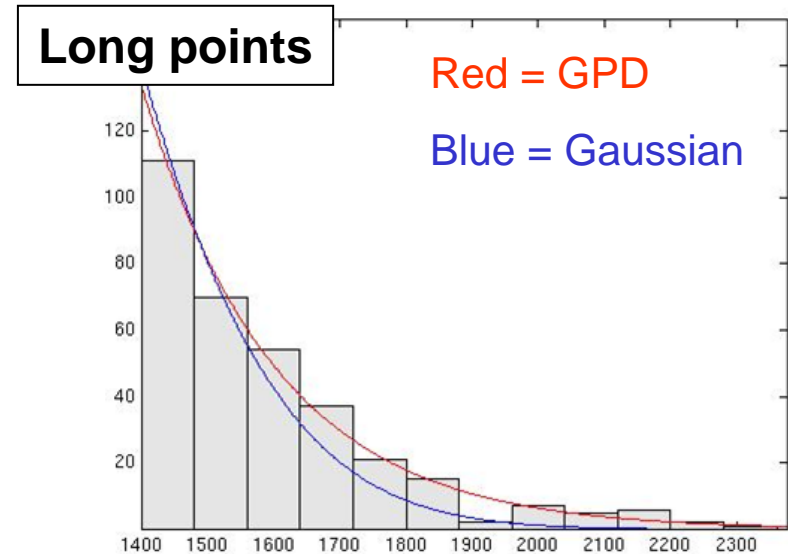
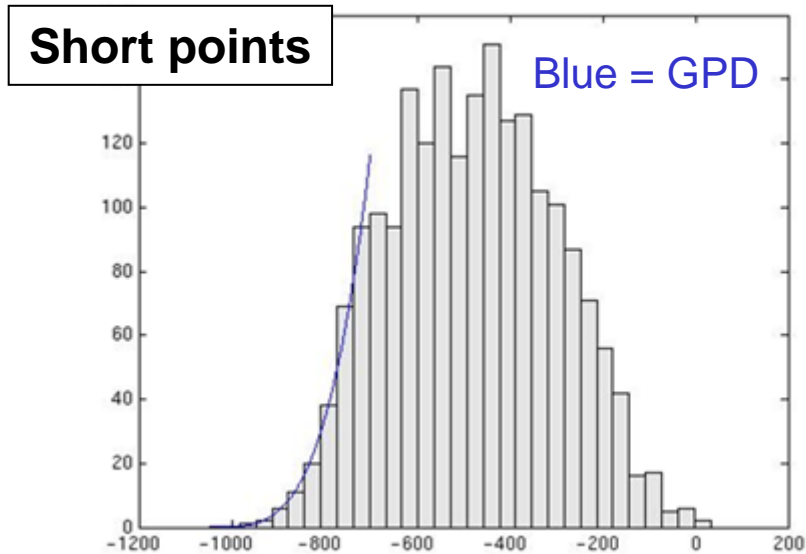
- $k$  = shape
- $\sigma$  = scale
- $\mu$  = translation



## Extreme values prediction

- ✓ Peaks Over Threshold method
  - ❑ Based on theoretical arguments
  - ❑ Consists in:
    - Defining a threshold value,
    - Discarding all data that are below the threshold
    - Fitting a GPD on the remaining data (known as exceedences)
  
- ✓ The choice of the threshold is critical
  
- ✓ It permits “the data to decide” which distribution is appropriate

## Extreme values prediction



- ❑ Matches the histogram better than the Gaussian law
- ❑ Numerical comparison between GPD and the empirical cumulative density of probability gives good results
- ✓ This method is adequate for computing safety boxes

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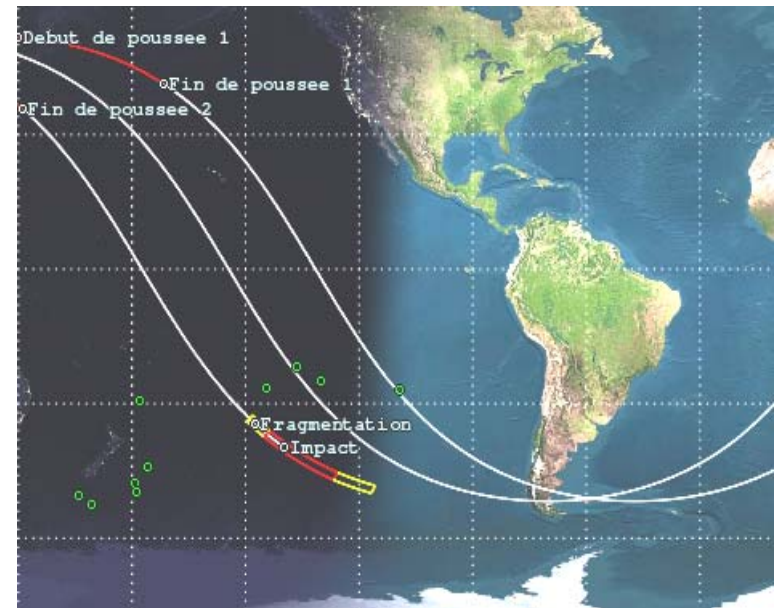
## Safety boxes for ATV Jules Verne re-entry

### ✓ Cross track boundaries for DRA and SRA

- ❑ +/- 100km from the ground track

### ✓ Along track boundaries

- ❑ Evaluated via GPD + POT method
- ❑ DRA length 2415 km
- ❑ SRA length 3050 km



### ✓ Majoring approaches in modeling have increased the safety

## Conclusions (2/3)

- ✓ Dedicated methods exist to deal with small probabilities
- ✓ Those methods are currently used in many safety fields
- ✓ and can also be used for **space safety**



- ✓ **Axis of improvement** for controlled re-entry safety
  - ❑ Modeling of surviving fragments
  - ❑ Occurrence of an explosion, altitude of explosion
  - ❑ Ejection velocities
- ✓ For this purpose, **ATV re-entry was observed** by two specially equipped planes



## ✓ *Questions*



